

Script generated by TTT

Title: Simon: Compilerbau (07.07.2014)

Date: Mon Jul 07 14:17:59 CEST 2014

Duration: 84:04 min

Pages: 80

Chapter 1: Data Structures in Memory

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Variables in Memory: L-Value and R-Value

Variables can be used in two different ways.

example: $a[x] = y + 1$

for y we need to know the value of the memory cell, for $a[x]$ we are interested in the **address**

r-value of x = content of x
l-value of x = address of x

compute r- and l-value in register R_i :

$code_R^i e \rho$	generates code to compute the r-value of e , given the environment ρ
$code_L^i e \rho$	analogously for the l-value

note:

Not every expression has an l-value (e.g.: $x + 1$).

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Address Environment

A variable by stored in four different ways:

- 1 Global: a variable is global
- 2 Local: ~~a~~ variable is stored on the stack frame
- 3 Register: a variable is stored in a local register R_i or a global register R_i

~~-~~ ~~-~~ ~~x = x~~

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accordingly, we define $\rho : Var \rightarrow \{G, L, R\} \times \mathbb{Z}$ as follows:

- $\rho x = \langle G, a \rangle$: variable x is stored at absolute address a
- $\rho x = \langle L, a \rangle$: variable x is stored at address $FP + a$
- $\rho x = \langle R, a \rangle$: variable x is stored in register R_a

Observe: a variable x can only have one entry in ρ
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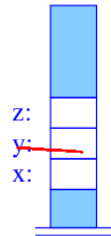
Observe: a variable x can only have one entry in ρ
However:

- ρ may be change with the program point
- that is, x may be assigned to a register at one point
- **and** to a memory location at another program point

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Necessity of Storing Variables in Memory

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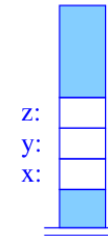
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Global variables:

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Necessity of Storing Variables in Memory



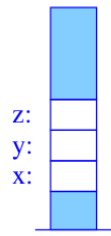
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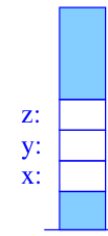
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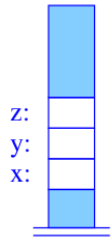
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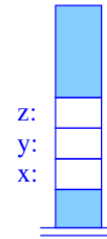
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Furthermore:

- a variable x (**int** or **struct**) whose address has been taken must be stored in memory, i.e. $\rho x = \langle L, o \rangle$ or $\rho x = \langle G, o \rangle$

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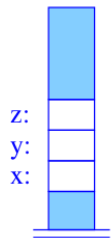
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- an access to an **array** is always done through a pointer, hence, it must be stored in memory
- optimization: store individual elements of a **struct** in register while no pointer accesses may reach the structure

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Translation of Statements

Statements such as $x = 2 * y$ have so far been translated by:

- computing the **r-value** of $2 * y$ in register R_i ,
- copying the content of R_i into the register $\rho(x)$

formally: let $\rho(x) = \langle R, j \rangle$ then:

$$\text{code}_R^i x = e_2 \rho = \text{code}_R^i e_2 \rho$$

$$\text{move } R_j R_i$$

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but: undefined result if $\rho x = \langle L, a \rangle$ or $\rho x = \langle G, a \rangle$.

idea:

- compute the r-value of e_2 in register R_i ,
- compute the l-value of e_1 in register R_{i+1} and
- write e_2 to address e_1 using a store instruction

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Translation of L-Values

new instruction: store $R_i R_j$ with semantics $S[R_i] = R_j$



definition for assignments:

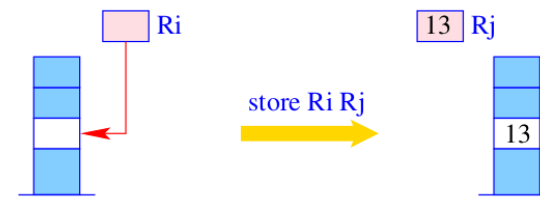
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So how do we translate $x = e$ (with $\rho x = \langle G, a \rangle$)?

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- Thus, for the case $e_1 = x$ and $\rho x = \langle R, j \rangle$ does not hold:

$$\text{code}_R^i e_1 = e_2 \rho = \text{code}_R^i e_2 \rho \\ \text{code}_L^{i+1} e_1 \rho \\ \text{store } R_{i+1} R_i$$

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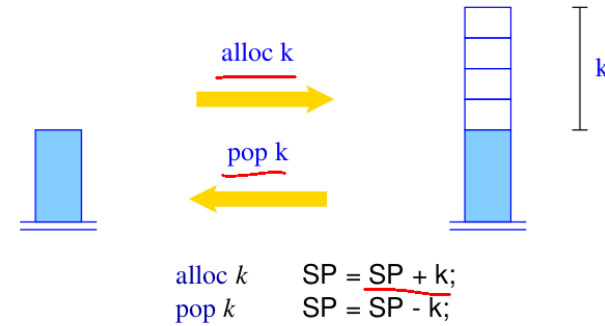
- The l-value of a variable is computed as follows:

$$\text{code}_L^i x \rho = \text{loadc } R_i a$$

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Allocating Memory for Local Variables

Given: a function with k local `int` variables that need to be stored in memory.



$$\begin{aligned} \text{alloc } k & \quad \text{SP} = \text{SP} + k; \\ \text{pop } k & \quad \text{SP} = \text{SP} - k; \end{aligned}$$

The instruction `alloc k` reserves space for k variables on the stack, `pop k` frees this space again.

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Access to Local Variables

Accesses to local variables are relative to FP. We therefore modify `codeL` to cater for variables in memory.

For $\rho x = \langle L, a \rangle$ we define

$$\text{code}_L^i x \rho = \text{loadrc } R_i a \text{ if } \rho x = \langle L, a \rangle$$

Instruction `loadrc R_i k` computes the sum of FP and k .



$$R_i = FP + k$$

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General Computation of the L-Value of a Variable

Computing the address of a variable in R_i is done as follows:

$$\text{code}_L^i x \rho = \begin{cases} \text{loadc } R_i a & \text{if } \rho x = \langle G, a \rangle \\ \text{loadrc } R_i a & \text{if } \rho x = \langle L, a \rangle \end{cases}$$

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Observations:

- intuitively: a register has no address
- during the compilation the l-value of a register may never be computed
- this requires a case distinction for assignments

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Analogously: for write operations we define:

$$\begin{aligned} \text{storer } a R_j &\equiv \text{loadrc } R_i a & \text{loadr} &\equiv \text{loadrc} \\ &\text{store } R_i R_j & \text{load} & \\ \text{storea } a R_j &\equiv \text{loadc } R_i a & \text{loada} &\equiv \text{loadc} \\ &\text{store } R_i R_j & \text{load} & \end{aligned}$$

i.e. `storea $a R_j$` is a **macro**. Define special case (where $\rho x = \langle G, a \rangle$):

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Data Transfer Instructions of the R-CMa

read- and write accesses of the R-CMa are as follows:

instruction	semantics	intuition
<code>load $R_i R_j$</code>	$R_i \leftarrow S[R_j]$	load value from address
<code>loada $R_i c$</code>	$R_i \leftarrow S[c]$	load global variable
<code>loadr $R_i c$</code>	$R_i \leftarrow S[FP + c]$	load local variable
<code>store $R_i R_j$</code>	$S[R_i] \leftarrow R_j$	store value at address
<code>storea $c R_i$</code>	$S[c] \leftarrow R_i$	write global variable
<code>storer $c R_i$</code>	$S[FP + c] \leftarrow R_i$	write local variable

instructions for computing addresses:

instruction	semantics	intuition
<code>loadc $R_i c$</code>	$R_i \leftarrow c$	load constant
<code>loadrc $R_i c$</code>	$R_i \leftarrow FP + c$	load constant relative to FP

instructions for general data transfer:

instruction	semantics	intuition
<code>move $R_i R_j$</code>	$R_i \leftarrow R_j$	transfer value between regs
<code>move $R_i k R_j$</code>	$[S[SP + i + 1]]_{i=0}^{k-1} \leftarrow S[R_j + i]$ $R_i \leftarrow SP + 1; SP \leftarrow SP + k$	copy k values onto stack

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Determining the Address-Environment

variables in the symbol table are tagged in one of three ways:

- 1 global variables, defined outside of functions (or as `static`); $\langle G, 7 \rangle$
- 2 local (automatic) variables, defined inside functions, accessible by pointers; $\langle R, 5 \rangle$
- 3 register (automatic) variables, defined inside functions.

Example:

```
int x, y;
void f(int v, int w) {
    int a;
    if (a > 0) {
        int b;
        g(&b);
    } else {
        int c;
    }
}
```

v	$\rho(v)$
x	$\langle G, 42 \rangle$
y	$\langle G, 40 \rangle$
v	$\langle R, -1 \rangle$
w	$\langle R, -2 \rangle$
a	$\langle R, 1 \rangle$
b	$\langle R, 0 \rangle$
c	$\langle R, 2 \rangle$

$$*(2x + 1) = 5$$

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w	$\langle R, -2 \rangle$
a	$\langle R, 1 \rangle$
b	$\langle L, 0 \rangle$
c	$\langle R, 2 \rangle$

Function Arguments on the Stack

- C allows for so-called *variadic functions*
- an unknown number of parameters: R_{-1}, R_{-2}, \dots
- **problem:** callee cannot index into global registers

example:

```
int printf(const char * format, ...);
char *s = "Hello_s!\nIt's_i_to_i!\n";
```

value	$\rho(p_i)$
s	$\langle R, -1 \rangle$
"World"	$\langle L, -3 \rangle$
5	$\langle L, -4 \rangle$
12	$\langle L, -5 \rangle$

```
int main(void) {
    printf(s, "World", 5, 12);
    return 0;
}
```

idea:

- push *variadic* parameters from *right to left* onto the stack
- the first parameter lies right below **PC, FP, EP**
- for a prototype $\tau f(\tau_1 x_1, \dots, \tau_k x_k, \dots)$ we set:

$$\begin{aligned}
 x_1 &\mapsto \langle R, -1 \rangle & x_k &\mapsto \langle R, -k \rangle \\
 x_{k+1} &\text{ at } \langle L, -3 \rangle & x_{k+i} &\text{ at } \langle L, -3 - |\tau_{k+1}| - \dots - |\tau_{k+i-1}| \rangle
 \end{aligned}$$

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Variables in Memory

Chapter 2: Arrays and Pointers

int flat

Translation of Array Accesses

Extend `codeL` and `codeR` with indexed array accesses.

Let `t[c] a;` be the declaration of an array *a*.

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Translation of Array Accesses

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Let $t[c] \ a;$ be the declaration of an array a .

In order to compute the address of $a[i]$, we need to compute $\rho a + |t| * (R\text{-Wert von } i)$. Thus:

$$\begin{aligned} \text{code}_L^i e_2[e_1] \rho &= \text{code}_R^i e_1 \rho \\ &\quad \text{code}_R^{i+1} e_2 \rho \\ &\quad \text{loadc } R_{i+2} |t| \\ &\quad \text{mul } R_i R_{i+2} R_{i+2} \\ &\quad \text{add } R_i R_i R_{i+1} \end{aligned}$$

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C structs (Records)

Note:

The same field name may occur in different `structs`

Here: The **component environment** ρ_{st} relates to the currently translated structure st .

Let `struct { int a; int b; } x;` be part of a declaration list.

- x is a variable of the size of (at least) the sum of the sizes of its fields
- we populate ρ_{st} with addresses of fields that are *relative* to the beginning of x , here $a \mapsto 0, b \mapsto 1$.

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Note:

- An array in C is simply a *pointer*. The declared array a is a *pointer constant*, whose r-value is address of the first field of a .
- Formally, we compute the r-value of a field e as $\text{code}_R^i e \rho = \text{code}_L^i e \rho$
- in C the following are equivalent (as l-value, not as types):

$$\underline{2[a]} \quad \underline{a[2]} \quad \underline{a+2}$$

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- x is a variable of the size of (at least) the sum of the sizes of its fields
- we populate ρ_{st} with addresses of fields that are *relative* to the beginning of x , here $a \mapsto 0, b \mapsto 1$.

In general, let $t \equiv \text{struct } \{ t_1 v_1; \dots; t_k v_k \}$, then

$$|t| := \sum_{i=1}^k |t_i| \quad \rho_{st} v_1 := 0 \quad \rho_{st} v_i := \rho_{st} v_{i-1} + |t_{i-1}| \quad \text{für } i > 1$$

We obtain:

$$\begin{aligned} \text{code}_L^i (e.c) \rho &= \text{code}_L^i e \rho \\ &\quad \text{loadc } R_{i+1} (\rho_{st} c) \\ &\quad \text{add } R_i R_i R_{i+1} \end{aligned}$$

$e.c = _$

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Pointer in C

Computing with pointers means

- 1 to create pointers, that is, to obtain the address of a variable;
- 2 to dereference pointers, that is, to access the pointed-to memory

Creating pointers:

- through the use of the address-of operator: $\&$ yields a pointer to a variable, that is, its (\neq l-value). Thus define:

$$\text{code}_R^i \&e \rho = \text{code}_L^i e \rho$$

Example:

Let `struct { int a; int b; } x;` with $\rho = \{x \mapsto 13\}$ and

$\rho_{st} = \{a \mapsto 0, b \mapsto 1\}$.

Then

$$\text{code}_L^i (x.b) \rho = \text{loadc } R_{i+1} \ 13$$

code_Rⁱ &x.b

$$\text{loadc } R_i \ 1$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

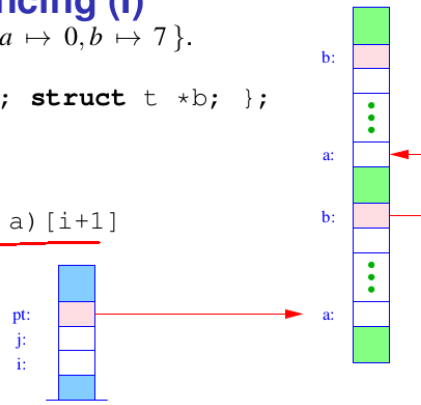
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Translation of Dereferencing (I)

Let $\rho = \{i \mapsto 1, j \mapsto 2, pt \mapsto 3, a \mapsto 0, b \mapsto 7\}$.

```
struct t { int a[7]; struct t *b; };
int i, j;
struct t *pt;
```

Translate $e \equiv ((pt \rightarrow b) \rightarrow a)[i+1]$



Then we have:

$$\text{code}_L^i e \rho = \text{code}_L^i ((pt \rightarrow b) \rightarrow a) \rho = \text{code}_L^i ((pt \rightarrow b) \rightarrow a) \rho$$

$$\text{code}_R^{i+1} (i+1) \rho$$

$$\text{loadc } R_{i+2} \ 1$$

$$\text{mul } R_{i+1} \ R_{i+1} \ R_{i+2}$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

$$\text{loada } R_{i+1} \ 1$$

$$\text{loadc } R_{i+2} \ 1$$

$$\text{add } R_{i+1} \ R_{i+1} \ R_{i+2}$$

$$\text{loadc } R_{i+2} \ 1$$

$$\text{mul } R_{i+1} \ R_{i+1} \ R_{i+2}$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

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Dereferencing Pointers

Applying the $*$ operator to an expression e yields the content of the cell whose l-value is stored in e :

$$\text{code}_R^i *e \rho = \text{code}_R^i e \rho$$

$$\text{load } R_i \ R_i$$

Example: Consider

```
struct t { int a[7]; struct t *b; };
int i, j;
struct t *pt;
```

and the expression $e \equiv ((pt \rightarrow b) \rightarrow a)[i+1]$

Since $e \rightarrow a \equiv (*e) . a$ we get:

$$\text{code}_L^i (e \rightarrow a) \rho = \text{code}_L^i e \rho$$

$$\text{loadc } R_{i+1} \ (\rho a)$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

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Translation of Dereferencing (II)

For dereferences of the form $(*e) . a$ the r-value is equal to the dereferencing of the l-value of e plus the offset of a . Thus, we define:

$$\text{code}_L^i ((pt \rightarrow b) \rightarrow a) \rho = \text{code}_L^i (pt \rightarrow b) \rho = \text{loada } R_i \ 3$$

$$\text{loadc } R_{i+1} \ 0$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

$$\text{load } R_i \ R_i$$

$$\text{loadc } R_{i+1} \ 0$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

Overall, we obtain the sequence:

$$\text{loada } R_i \ 3$$

$$\text{loadc } R_{i+1} \ 7$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

$$\text{load } R_i \ R_i$$

$$\text{loadc } R_{i+1} \ 1$$

$$\text{loadc } R_{i+2} \ 1$$

$$\text{mul } R_{i+1} \ R_{i+1} \ R_{i+2}$$

$$\text{add } R_i \ R_i \ R_{i+1}$$

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Passing Compound Parameters

Consider the following declarations:

```
typedef struct { int x, y; } point_t;  
int distToOrigin(point_t);
```

~> How do we pass parameters that are not basis types?

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Passing Compound Parameters

Consider the following declarations:

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- idea: caller passes a pointer to the structure

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- problem: callee could modify the structure

for

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Passing Compound Parameters

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int distToOrigin(point_t);
```

~> How do we pass parameters that are not basis types?

- idea: caller passes a pointer to the structure
- problem: callee could modify the structure
- solution: caller passes a pointer to a copy

f() {
 p' = point_t;
 distToOrigin(&p');
}

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Passing Compound Parameters

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```
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int distToOrigin(point_t);
```

~> How do we pass parameters that are not basis types?

- **idea:** *caller* passes a pointer to the structure
- **problem:** *callee* could modify the structure
- **solution:** *caller* passes a pointer to a copy

$$\text{code}_R^i e \rho = \text{code}_L^{i+1} e \rho$$

move R_i k R_{i+1} e a structure of size k

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Variables in Memory

Chapter 3: The Heap

Passing Compound Parameters

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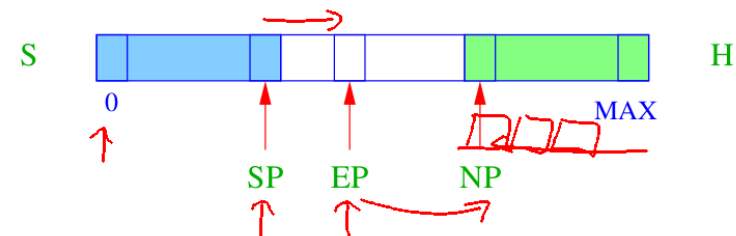
new instruction: *move*

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The Heap

Pointer all the use dynamic data structure that are allocated on the heap and whose life-time does not have to follow the LIFO-allocation scheme of the stack.

~> we need an arbitrary large memory area H, called the heap; implementation:



- NP $\hat{=}$ new pointer; points to the first unused heap cell
- EP $\hat{=}$ extreme pointer; points to the cell that SP may maximally point (changes during function call/return).

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Invariant of Heap and Stack

- the stack and the heap may not overlap

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Invariant of Heap and Stack

- the stack and the heap may not overlap
- an overlap may only happen when SP is incremented (stack overflow) or
- when NP is decremented (out of memory)
 - in contrast to a stack overflow, an out of memory error can be communicated to the programmer
 - malloc returns NULL in this case which is defined as (void*) 0

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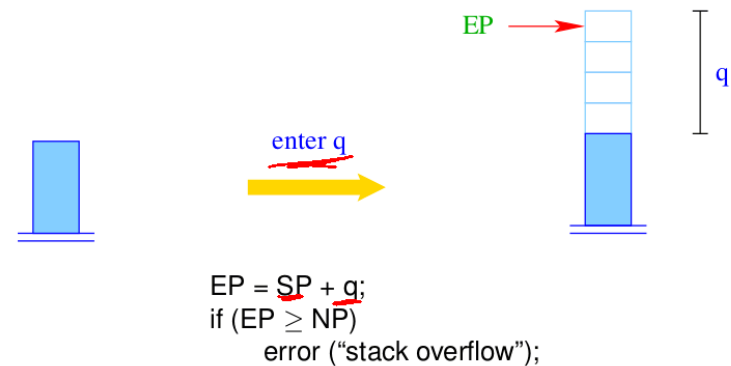
Invariant of Heap and Stack

- the stack and the heap may not overlap
- an overlap may only happen when SP is incremented (stack overflow) or
- when NP is decremented (out of memory)
 - in contrast to a stack overflow, an out of memory error can be communicated to the programmer
 - malloc returns NULL in this case which is defined as (void*) 0
- EP reduces the necessary check to a single check upon entering a function
- the check for each heap allocation remains necessary

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Reserving Memory on the Stack

The instruction `enter q` sets EP to the last stack cell that this function will use.



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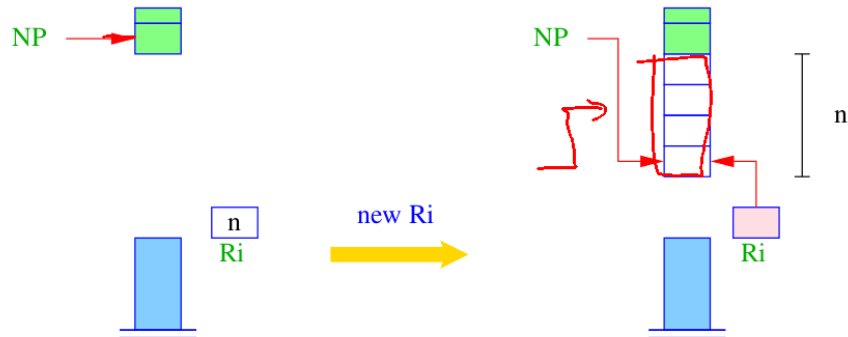
Dynamically Allocated Memory

In order to implement `malloc`, its use is directly translated into instructions:

- a call to `malloc` must return a pointer to a heap cell:

$$\text{code}_R^i \text{ malloc}(e) \rho = \text{code}_R^i e \rho$$

new R_i



```
if (NP - R[i] <= EP) R[i] = NULL; else {
    NP = NP - R[i];
    R[i] = NP;
}
```

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Possible Implementations of free

- 1 Leave the problem of dangling pointers to the programmer. Use a data structure to manage allocated and free memory. \leadsto `malloc` becomes expensive
- 2 Do nothing:

$$\text{code}_R^i \text{ free}(e) \rho = \text{code}_R^i e \rho$$

\leadsto simple and efficient, but not for reactive programs

- 3 Use an `automatic`, possibly "conservative" `garbage collection`, that occasionally runs to reclaim memory that `certainly` is not in use anymore. Make this re-claimed memory available again to `malloc`.

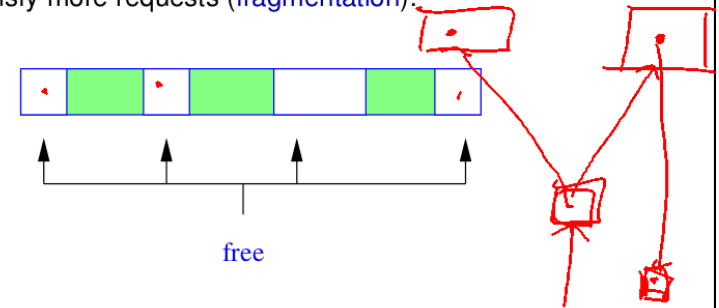
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Freeing Memory

A region allocated with `malloc` may be deallocated using `free`.

Problems:

- the freed memory could still be accessed, thereby accessing memory that may have a new owner (`dangling references`).
- interleaving `malloc` and `free` may not leave a larger enough block to satisfy more requests (`fragmentation`):



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Variables in Memory

~~Chapter 4:~~

~~Translating Functions and Programs with Heap~~



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Instructions for Starting a Program

A program $P = F_1; \dots F_n$ has to have one main function.

```
code1 P ρ =
  enter (k + 3)
  alloc k
  loadc R1 _main
  saveloc R1 R0
  mark
  call R1
  restoreloc R1 R0
  halt
  f1 : codei F1 ρ ⊕ ρf1
  ⋮
  fn : codei Fn ρ ⊕ ρfn
```



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  f1 : codei F1 ρ ⊕ ρf1
  ⋮
  fn : codei Fn ρ ⊕ ρfn
```

assumptions:

- k are the number of stack location set aside for global variables
- saveloc R₁ R₀ has no effect (i.e. it backs up no register)
- ρ contains the address of all functions and global variable

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Translation of Functions

The translation of a function is modified as follows:

```
codel tr f(args){decls ss} ρ =
  enter q
  alloc k
  move Rl+1 R-1
  ⋮
  move Rl+n R-n
  codel+n+1 ss ρ'
  return
```

side conditions:

Randbedingungen:

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Randbedingungen:

- enter ensures that enough stack space is available (q : number of required stack cells)

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Translation of Functions

The translation of a function is modified as follows:

```
codel tr f(args){decls ss} ρ = enter g
                                alloc k
                                move Rl+1 R-1
                                ⋮
                                move Rl+n R-n
                                codel+n+1 ss ρ'
                                return
```

Randbedingungen:

- **enter** ensures that enough stack space is available (g : number of required stack cells)
- **alloc** reserves space on the stack for local variables ($k < g$)

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Translation of Function Calls

The function call $g(e_1, \dots, e_n)$ is translated as follows:

```
codeRi g(e1, ... en) ρ = codeRi g ρ
                             codeRi+1 e1 ρ
                             ⋮
                             codeRi+n en ρ
                             move R-1 Ri+1
                             ⋮
                             move R-n Ri+n
                             saveloc R1 Ri-1
                             mark
                             call Ri
                             restoreloc R1 Ri-1
                             pop k
                             move Ri R0
```

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Translation of Function Calls

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                             ⋮
                             move R-n Ri+n
                             saveloc R1 Ri-1
                             mark
                             call Ri
                             restoreloc R1 Ri-1
                             pop k
                             move Ri R0
```

Difference to previous scheme:

- we assume that g has n arguments, that is, it is not *variadic*
- new instruction **pop** : removes stack cells which have been allocated in code_R^{i+j} e_j ρ

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Peephole Optimization

The generated code contains many redundancies, such as:

```
move R7 R7

pop 0

move R5 R7
mul R4 R4 R7
```

Peephole optimization matches certain patterns and replaces them by simpler patterns

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Realistic Register Machiens

The R-CMa is a virtual machine that makes it easy to generate code.

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~~==~~

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- real processors have a fixed number of registers
- the infinite set of *virtual* registers of the R-CMa must be mapped onto a finite set of processor registers
- idea: use a register R_i that is currently not in use for the content of R_j
- in case the program needs more register at one time than available, we need to *spill* registers onto the stack

We thus require solutions to the following problems:

~~_____~~

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Realistic Register Machiens

The R-CMa is a virtual machine that makes it easy to generate code.

- real processors have a fixed number of registers
- the infinite set of *virtual* registers of the R-CMa must be mapped onto a finite set of processor registers
- idea: use a register R_i that is currently not in use for the content of R_j $R \neq R$
- in case the program needs more register at one time than available, we need to *spill* registers onto the stack

We thus require solutions to the following problems:

- determine when a register is not *live* (in use)
- map several *virtual* registers to the same *processor* register if they are not live at the same time

these problems are addressed in the lecture on *Program Optimization*.

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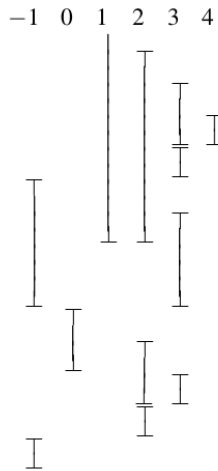
Register Coloring for the fac-Function

Note: def-use liveness

```
int fac(int x) {
  if (x<=0) then
    return 1;
  else
    return x*fac(x-1);
}
```

```
_fac:  enter 5
      move R1 R_{-1}
      move R2 R1
      loadc R3 0
      leq R2 R2 R3
      jumpz R2 _A
      loadc R2 1
      move R0 R2
      return
      jump _B
```

```
_A:  move R2 R1
      move R3 R1
      loadc R4 1
      sub R3 R3 R4
      move R_{-1} R3
      loadc R3 _fac
      saveloc R1 R2
      mark
      call R3
      restoreloc R1 R2
      move R3 R0
      mul R2 R2 R3
      move R0 R2
      return
_B:  return
```



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Outlook

register allocation has several other uses:

- remove unnecessary `move` instructions

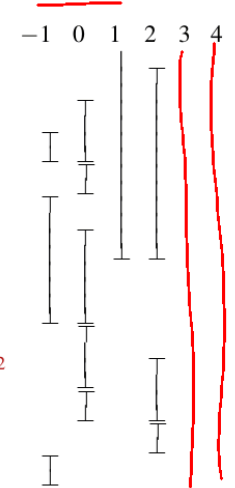
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      restoreloc R1 R2
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      mul R2 R2 R0
      move R0 R2
      return
_B:  return
```



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Outlook

register allocation has several other uses:

- remove unnecessary `move` instructions
- decide which variable to spill onto the stack
 - \rightsquigarrow this might in turn require more registers
- translation into `single static assignment` form simplifies analysis
- optimal register allocation possible (but registers might need to be permuted at the end of basic blocks)

\rightsquigarrow lecture on *Program Optimization*

schematically presented `liveness`-analysis can be improved:

- x is only live after $x \leftarrow y + 1$ if y was live
- `saveloc` keeps registers unnecessarily alive \rightsquigarrow intermediate representation

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\leadsto lecture on *Program Optimization*

schematically presented `liveness`-analysis can be improved:

- x is only live after $x \leftarrow y + 1$ if y was live
- `saveloc` keeps registers unnecessarily alive \leadsto intermediate representation
- are there *optimal* rules for the `liveness`-analysis?