Script generated by TTT

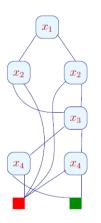
Title: Seidl: Programmoptimierung (04.02.2013)

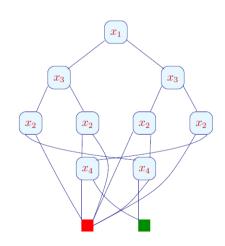
Date: Mon Feb 04 14:03:55 CET 2013

Duration: 86:40 min

Pages: 33

Example: $(x_1 \leftrightarrow x_2) \land (x_3 \leftrightarrow x_4)$





896

Discussion:

- Originally, BDDs have been developped for circuit verification.
- Today, they are also applied to the verification of software ...
- A system state is encoded by a sequence of bits.
- A BDD then describes the set of all reachable system states.
- Warning: Repeated application of Boolean operations may increase the size dramatically!
- The variable ordering may have a dramatic impact ...

895

Discussion (2):

• In general, consider the function:

$$(x_1 \leftrightarrow x_2) \land \ldots \land (x_{2n-1} \leftrightarrow x_{2n})$$

W.r.t. the variable ordering:

$$x_1 < x_2 < \ldots < x_{2n}$$

the BDD has 3n internal nodes.

W.r.t. the variable ordering:

$$x_1 < x_3 < \ldots < x_{2n-1} < x_2 < x_4 < \ldots < x_{2n}$$

the BDD has more than 2^n internal nodes!!

 A similar result holds for the implementation of Addition through BDDs.



hrenz

Discussion (3):

- Not all Boolean functions have small BDDs :-(
- Difficult functions:
 - □ multiplication;
 - ☐ indirect addressing ...
 - → data-intensive programs cannot be analyzed in this way :-(

898

Example:

$$\begin{array}{llll} \mathsf{bigger}(X,Y) & \leftarrow & X = elephant, Y = horse \\ \mathsf{bigger}(X,Y) & \leftarrow & X = horse, Y = donkey \\ \mathsf{bigger}(X,Y) & \leftarrow & X = donkey, Y = dog \\ \mathsf{bigger}(X,Y) & \leftarrow & X = donkey, Y = monkey \\ \mathsf{is_bigger}(X,Y) & \leftarrow & \mathsf{bigger}(X,Y) \\ \mathsf{is_bigger}(X,Y) & \leftarrow & \mathsf{bigger}(X,Z), \mathsf{is_bigger}(Z,Y) \\ & \leftarrow & \mathsf{is_bigger}(elephant, dog) \end{array}$$

Perspectives: Further Properties of Programs

Freeness: Is X_i possibly/always unbound?

 \Longrightarrow

If X_i is always unbound, no indexing for X_i is required :-)

Pair Sharing: Are X_i , X_j possibly bound to terms t_i , t_j with

If X_i is never unbound, indexing for X_i is complete :-)

 $Vars(t_i) \cap Vars(t_i) \neq \emptyset$?

Literals without sharing can be executed in parallel:-)

Remark:

Both analyses may profit from Groundness!

899

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A more realistic Example:

$$\begin{split} \operatorname{app}(X,Y,Z) &\leftarrow X = [\;], \ Y = Z \\ \operatorname{app}(X,Y,Z) &\leftarrow X = [H|X'], \ Z = [H|Z'], \ \operatorname{app}(X',Y,Z') \\ &\leftarrow \operatorname{app}(X,[Y,c],[a,b,Z]) \\ & & & & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\$$

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Remark:

$$[] \hspace{1cm} = \hspace{1cm} \text{the atom empty list} \\ [H|Z] \hspace{1cm} = \hspace{1cm} \text{binary constructor application} \\ [a,b,Z] \hspace{1cm} = \hspace{1cm} \text{Abbreviation for: } [a|[b|[Z|[\]]]]$$

873

Accordingly, a program p is constructed as follows:

$$t ::= a \mid X \mid_{-} \mid f(t_1, \dots, t_n)$$

$$g ::= p(t_1, \dots, t_k) \mid X = t$$

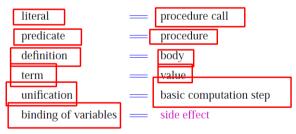
$$c ::= p(X_1, \dots, X_k) \leftarrow g_1, \dots, g_r$$

$$q ::= \leftarrow g_1, \dots, g_r$$

$$p ::= c_1 \dots c_m q$$

- A term t either is an atom, a (possibly anonymous) variable or a constructor application.
- A goal g either is a literal, i.e., a predicate call, or a unification.
- A clause c consists of a head $p(X_1, \ldots, X_k)$ together with body consisting of a sequence of goals.
- A program consists of a sequence of clauses together with a sequence of goals as query.

Procedural View of PuP-Programs:



Warning: Predicate calls ...

- do not return results!
- modify the caller solely through side effects :-)
- may fail. Then, the following definition is tried backtracking

875

Inefficiencies:

Backtracking: • The matching alternative must be searched for ⇒ Indexing

• Since a successful call may still fail later, the stack can only be cleared if there are no pending alternatives.

Unification: • The translation possibly must switch between build and check several times.

 In case of unification with a variable, an Occur Check must be performed.

Type Checking: • Since Prolog is untyped, it must be checked at run-time whether or not a term is of the desired form.

Otherwise, ugly errors could show up.

876

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$\frac{1}{2} = \frac{1}{2}$, $\frac{1}{2} = \frac{1}{2}$

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Some Optimizations:

- Replacing last calls with jumps;
- Compile-time type inference;
- Identification of deterministic predicates ...

Example:

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877

5.1 Groundness Analysis

A variable X is called ground w.r.t. a program execution π starting program entry and entering a program point v, if X is bound to a variable-free term.

Goal:

- Find all variables which are ground whenever a particular program point is reached!
- Find all arguments of a predicate which are ground whenever the predicate is called!

P(out, in)

Observation:

- In PuP, functions must be simulated through predicates.
- These then have designated input- and output parameters.
- Input parameters are those which are instantiated with a variable-free term whenever the predicate is called.

These are also called ground.

- In the example, the first parameter of app is an input parameter.
- Unification with such a parameter can be implemented as pattern matching!
- Then we see that app in fact is deterministic !!!

878

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Idea:

• Describe groundness by values from **B**:

1 == variable-free term;

0 = term which contains variables.

• A set of variable assignments is described by Boolean functions :-)

$$X \leftrightarrow Y = X$$
 is ground iff Y is ground. $X \land Y = X$ and Y are ground.

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Idea (cont.):

- The constant function 0 denotes an unreachable program point.
- Occurring sets of variable assignments are closed under substitution. This means that for every occurring function $\phi \neq 0$,

$$\phi(1,\ldots,1)=1$$

These functions are called positive.

• The set of all positive functions is called Pos.

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• In particular, the least element is 0 :-)

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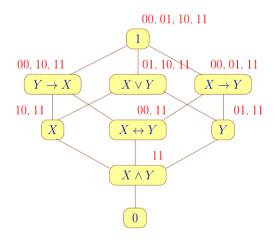
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881

Example:



882

Remarks:

- Not all positive functions are monotonic !!!
- For k variables, there are $2^{2^{k-1}} + 1$ many functions.
- The height of the complete lattice is 2^k.
- We construct an interprocedural analysis which for every predicate p determines a (monotonic) transformation

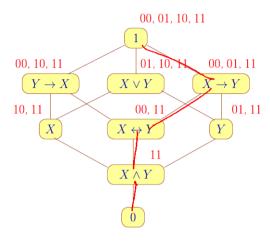
$$\llbracket p \rrbracket^{\sharp} : \mathsf{Pos} \to \mathsf{Pos}$$

• For every clause, $p(X_1, \ldots, X_k) \Leftarrow g_1, \ldots, g_n$ we obtain the constraint:

$$\llbracket p \rrbracket^{\sharp} \psi \quad \supseteq \quad \exists X_{k+1}, \dots, X_m. \, \llbracket g_n \rrbracket^{\sharp} (\dots (\llbracket g_1 \rrbracket^{\sharp} \psi) \dots)$$

// m number of clause variables

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Abstract Unification:

$$[X = t]^{\sharp} \psi = \psi \wedge (X \leftrightarrow X_1 \wedge \ldots \wedge X_r)$$
if $Vars(t) = \{X_1, \ldots, X_r\}.$

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884

Thereby:

$$\begin{split} & \mathrm{enter}_{s_1,\dots,s_k}^{\sharp}\psi \ = \ \mathrm{ren}\,(\exists\, X_1,\dots,X_m.\ [\![\bar{X}_1=s_1,\dots,\bar{X}_k=s_k]\!]^{\sharp}\psi) \\ & \mathrm{combine}_{s_1,\dots,s_k}^{\sharp}(\psi,\psi_1) \ = \ \exists\, \bar{X}_1,\dots,\bar{X}_r.\ \psi \wedge [\![\bar{X}_1=s_1,\dots,\bar{X}_k=s_k]\!]^{\sharp}(\overline{\mathrm{ren}}\,\psi_1) \end{split}$$

$$\begin{array}{lcl} \exists\,X.\,\phi &=& \phi[0/X]\vee\phi[1/X] \\ \operatorname{ren}\phi &=& \phi[X_1/\bar{X}_1,\ldots,X_k/\bar{X}_k] \\ \\ \overline{\operatorname{ren}}\,\phi &=& \phi[\bar{X}_1/X_1,\ldots,\bar{X}_r/X_r] \end{array}$$